

## AMENDMENTS TO THE SPECIFICATION

Please amend the specification on Page 14, after Line 3 by adding the following:

Figure 9 is a an isometric view of a typical pine cone which may be collected by my tool.

Figure 10 is a partial isometric view of a pine cone entering the instant collection tool.

Figure 11 is a somewhat enlarged isometric view of the pine cone of Figure 10 passing into and partially through the entry structure of the instant collection tool.

Please amend the specification from Page 20, Line 20 to Page 22, Line 21 as follows:

A tool is formed according the foregoing specification and manually moved to the location of a pine cone 30 (Fig. 1) to be collected. The tool is placed with the entry structure **12** resting on and immediately above the subject pine cone 30. The tool then is grasped by manipulating handles **11** and forced downwardly until the lower edge of annular peripheral rim **24** rests on the surface supporting the subject pine cone 30. As the entry structure **12** moves downwardly relative to the pine cone 30 therebeneath, portions of the fingers **25** will be deformed by the pine cone 30 and the pine cone 30

will ultimately pass through the orifice defined by spaces **28,29**, move into the medial channel **14** of body tube **13**. As the pine cone **30** moves through the entry structure **12** the fingers **25** of entry structure **12** by reason of retentent memory, will return to their null state that existed before deformation and the tool will be ready for a second similar pine cone collecting operation as described.

The collected pine cone **30** in medial channel **14** of the cylindrical tube **13** will be retained within the tube **13** because there is no external force in the body channel **14** upon the pine cone **30** to allow it to deform fingers **25** to move outwardly therepast and the force of gravity acting upon the pine cone **30** and any other pine cones **30** in the body channel **14** is not sufficient to cause such action.

The pine cone **30** collecting process then is continued in a similar fashion until a quantity of pine cones **30** is carried within medial channel **14** of the body **10**. At this point when the collecting operation has been completed or the body **10** reasonably filled with pine cones **30**, the tool is manually moved to a disposition sight spacedly above the area where pine cones **30** are to be deposited. The tool is manually manipulated to turn it upside-down and the pine

cones 30 carried in medial channel **14** of the body **10** will move by action of gravity outwardly from the open upper end portion **15** of body **10** and be deposited somewhat vertically therebelow.

In using the instant tool it is to be noted that both the tool and a pine cone 30 to be collected thereby may easily be moved relative to each other to better position a pine cone 30 in a loading position or to better accomplish the passage of the pine cone 30 through the entry structure **12** and into the tool body **10**. This movement, the entire loading operation and unloading operation may be accomplished by the user while in a standing position and without any manual contact with the pine cones 30 in the entire collection and disposition process.